eliv/ell

RGF 300 Three-phase voltage regulator



WARNING !



HIGH LEAKAGE CURRENT: first connect to earth !

The rgf300 is a voltage regulator for three phase motors which operates connected to the three phase mains voltage. The regulator must be installed by qualified personnel who will connect the electric supply, attach the cables in their permanent positions and commission the plant.

Incorrect installation of the rgf300 voltage regulator or the fan connected to it may cause damage to objects or people so ensure the instructions in this manual and all required security measures are read and followed carefully.

- When receiving the goods, check that the packing is intact; in the event of any damage due to transportation, notify the forwarding agent according to legal requirements.
- The rgf series of products shown in this manual has been manufactured to the highest standards.
- The manufacturer declines all responsibility for accident, loss or damage caused by the use of these appliances. These must be correctly installed by qualified personnel in conformity with their destined use and, whenever needed, must undergo correct maintenance which should be carried out while ensuring the safety of people, domestic animals and goods.
- The purchaser must previously ascertain the suitability of the product for the use it is intended for and assume all consequent risks and responsibility.
- The rgf300 is a mains voltage regulator which uses the phase-cut principle completely controlled over the three phases. It has been designed to vary the effective voltage on three phase asynchronous motors for fans following a control signal (either mA, VDC or Ohm). The appliance is manufactured for industrial use and therefore meets the EMC standards that relate to industrial environments.
- Using the appliance for purposes other than the ones described above will be considered incorrect. In particular, the appliance may <u>NOT</u> be used to supply machine tools or any other machines where the motor torque-speed characteristic is not quadratic.
- If the equipment is intended for civil, commercial and/or light industrial use, supplementary components and other types of equipment are required which can be supplied on specific request from the purchaser. In this case, the purchaser must provide a suitable design of the plant in which the appliance is to be installed (compliant with EN 60555 2/3 standards regarding disturbance produced by electrical household appliances and the like.

• We decline all responsibility for any errors in the catalogues, publications or other written documents. The information in this manual is not binding and we reserve the right to make changes to the products without prior notice, at any time and in any way that we deem convenient for production purposes or useful for increasing functionality and performance.



SAFETY RULES !



This appliance has been designed to give excellent performance provided it is installed and used carefully in a suitable electric environment by qualified personnel.

The following rules **must be obeyed** when installing the regulator :

- Follow the instructions in this manual exactly and observe all safety measures in force.
- Do NOT tamper with or disassemble the regulator's internal components; doing so will INVALIDATE THE GUARANTEE and may cause unnecessary damage.
- The regulator does not contain components that can be repaired by the user.
- The regulator must be suitably and effectively earthed by the installer according to the standards in force; earthing is essential for the EMC filter to operate correctly.
- The user must be protected from the electric supply and the motor must be protected from possible overloads in compliance with the standards in force.
- **DO NOT** supply the regulator without the internal protection panel made from lexan.
- **DO NOT** touch the electrical parts of the circuit when the power supply is connected under any circumstances.
- Before supplying power to the unit, check carefully that the power and earth are correctly connected.
- If the mains supply is "disturbed", which may be due to other electrical power components causing irregularities in the supply (power contactors), it is recommended that supplementary three phase 'SURGE ARRESTER' filters are installed directly on the regulator supply.
- Avoid repeatedly connecting and disconnecting the power supply to the regulator; a constant supply keeps the regulator at working temperature and eliminates problems caused by condensate inside the protection case.
- Alternatively, use the remote terminal board contact 'MB' S2 = ON/OFF.
- The S2 = ON/OFF contact on the MB terminal board does not cut the mains supply and therefore cannot be used as a safety switch.
- Install the regulator out of direct sunlight so that the container cannot get overheated and cause a reduction in the maximum load current.
- The appliance may operate at environmental temperatures up to 50°C. Do not install it where this temperature may be exceeded or the integrity of the regulator will be compromised and the appliance may make the user appliance operate at full load (100%) with all consequent effects.
- The appliance must be stood vertically to encourage heat dissipation and to ensure there is a sufficient air circulation and free space measuring **150 mm** above and below the regulator. If several regulators are to be grouped together on a single electric board, provide forced air circulation with a fan or cooling unit of sufficient power.
- Use the holes on the lower and power terminal board sides of the appliance, for entrance of the connection cables. This will prevent water, dust etc. from getting in and will ensure the **IP55** protection level is maintained using adequately sized cables and sheaths of suitable quality.
- Reassemble and check the cover of the external protection panel is properly closed.
- DO NOT alter or damage the identification stickers on the equipment.
- DO NOT force the trimmers to rotate beyond their set mechanical travel.
- Only alter the trimmers intended for regulation.
- Under no circumstances alter the trimmers marked with the spot of red paint.



WARNING ! HIGH LEAKAGE CURRENT: first connect to earth !



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1.0 PRESENTATION

THANK YOU for choosing an **rgf300** series three phase voltage regulator, designed specifically to give the maximum yield and greatest ease of use.

Like all our products, it has been built to the very highest quality standards using electronic components of the utmost reliability which have undergone functional tests that guarantee use of the product for at least **30,000 hours** of continuous operation without problem.

The **rgf300** regulator is a power unit designed to meet requirements of quality and flexibility of use in plants and machines in which proportional variation of the speed of rotation of the fans is essential.

The regulator is housed in a **GEWISS GW Plast® 120°C** case (**fig. 1**) which guarantees high heat resistance during ordinary use (120°C), increased mechanical impact resistance (IK = 08) and a protection level (**IP55**) that allows the regulator to be installed out of doors.

Inside the case there is a lexan protection panel displaying instructions for use and commissioning of the **rgf300**.

The 12A rgf300 is shown in fig. 1.

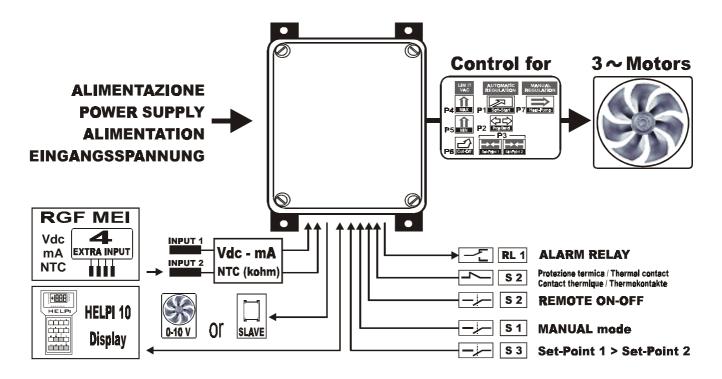
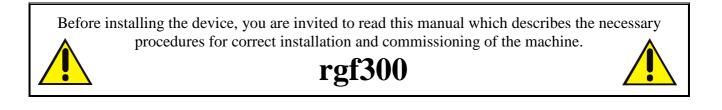


fig. 1



Like all our products, the **rgf300** series bears **CE** marking as required by directive **89/336/ECC** and its subsequent modification **EEC/92/31** on electromagnetic compatibility.

Since all these products are not used as "**stand alone**" appliances but incorporated into other plants or machines, the standards' compatibility test was carried out under typical operating conditions.

The essential requirements of the directive are satisfied by conformity to "generic standards" for heavy industry.



EN 50081-2 emission standard, EN 50082-2 immunity standard, and in particular:

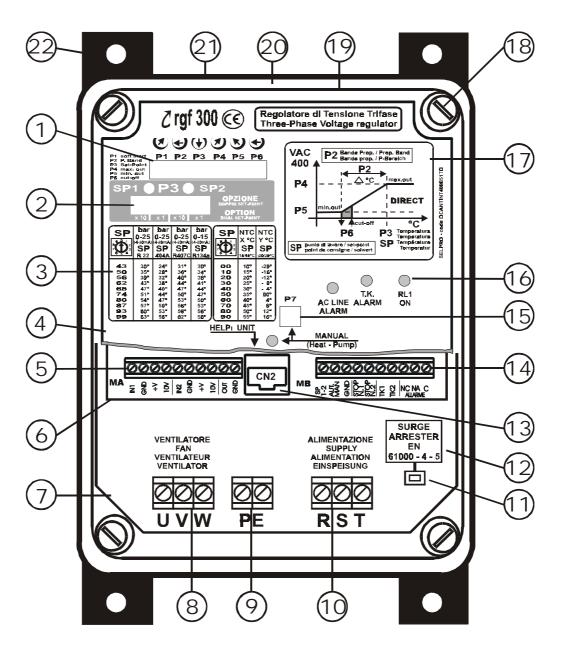
EN 55011	class B, for radiated disturbances
EN 55011	class A, for conducted disturbances
ENV 50140 (IEC 801-3)	for susceptibility (on the power supply)
ENV 50141	for conducted susceptibility on power lines
IEC 801-4	for fast transistors (bursts / high frequency disturbances)
IEC 801-2	for electrostatic discharge (ESD)

The tests and checks for conformity have been carried out according to the procedures described in the product's technical documentation. The system used was formed by an **rgf300** voltage regulator, a control cable and relative controls, a power supply cable, a motor cable and a fan.

fig. 2

Responsibility for the final characteristics of the system or plant regarding the EMC directive rests with the installer. The equipment must be installed in observance of the regulations in force using the information presented in this manual.

Fig. 3 represent the rgf300 regulator with the general contents



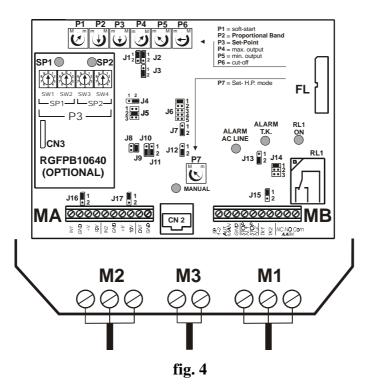


	CONTENTS of a	:gf3(00 regulator
1.	Control Trimmer for work parameters regulation	2.	Double 10 positions rotary switch for Set-point (optional)
3.	Reference table for Set-point rotary centesimal switch	4.	Lexan internal panel for protection against direct contact
5.	Terminal block for analog inputs/output signals	6.	Control card (upper)
7.	Power card (lower)	8.	Terminal block for load connection (U-V-W)
9.	Terminal block for PE connection	10.	Terminal block for threephase power supply (R-S-T)
11.	SURGE ARRESTER circuit / PE faston connection	12.	SURGE ARRESTER circuit like EN 61000-4-5
13.	CN2 connector for HELPI display unit	14.	Terminal block ON-OFF auxilary inputs/output signals
15.	Control Trimmer for Manual mode (heat-pump) regulation	16.	Status LED
17.	Characteristic with function parameters	18.	Cover screws
19.	Macrolon cover of the case	20.	GEWISS GW Plast ® 120°C case
21.	Black anodized heat sink	22.	Screws hole for wall installation

1.1 **DESCRIPTION**

The **rgf300** series three-phase cutting regulators comprises two electronic cards on a vetronite support mounted inside the **GEWISS IP55 GW Plast® 120°C** case.

The two cards represent the control section (upper) and power section (lower).



The control card contains the following regulation, connection and signalling components:

٠	trimmers	Marked " Pn "; used to set working parameters
•	centesimal switch	Marked "SW"; used for the simply Set-Point parameter, with 100 working points
		on the transducer skale (only with PB 1064 option)
•	relay	Marked " RL1 "
		Relay with commutation contact for external signalling of correct operation or
		stop (see selection jumper J14).
٠	Leds	Marked " Dln "
	AC LINE ALARM	RED Led DL1 to signal "regulator stop/fault"
	T.K. ALARM	RED Led DL2 to signal "external heat protection (T.K)."
	RL1 ON	GREEN Led DL3 to signal commutation relay RL1 in the N.O. position
	MANUAL	YELLOW Led DL4 to signal "HEAT PUMP" mode
•	jumpers	Marked 'Jn'; used to change preset operational modes
•	flat cable	Marked 'FL'
		The flat allows connection to the control and power cards.
		Check the flat is securely fixed during maintenance or commissioning.
•	CN2	Rapid connector to the portable HELPI10 unit for display of the rgf300 's work
		parameters
•	Inputs/output signals terminal boards	Terminal board MA for connection of the control analogue input signals Terminal board MB for connection of the ON-OFF inputs and outputs
	~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	J

The **power card** contains the following connection components:

•	power supply	'M1' for three-phase input supply R , S , T
	terminal boards	'M2' for three-phase output U, V, W
		'M3' for the Earth / PE connection

1.2 INSTALLATION AND MECHANICAL DIMENSIONS

The **rgf300** regulator must always be securely assembled and fixed using the four (4) attachment screws on the side fins before connecting to the power supply.

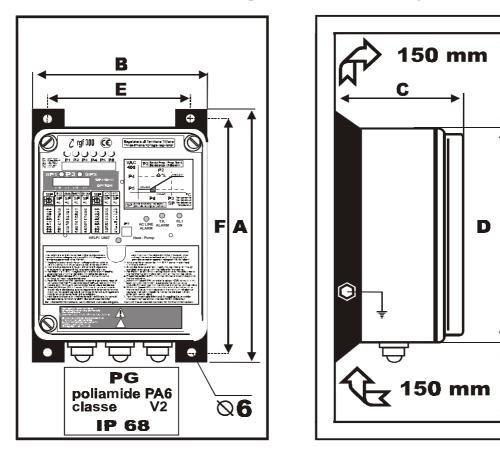
The holes provided on the lower part of the regulator are for entry of the electric connection cables:

- four pole line (three phase + Earth) to power the regulator,
- four pole line (three phase + Earth) to power the load,
- signal cable lines for the analogue inputs and digital outputs.

To make installation simpler, all regulators are also fitted with stuffing boxes in **PA6** polyamide, class **V2**, **IP68**, for use with the power and signal cables.

The regulator is cooled by natural convection and so air must be able to pass freely below and above the appliance.

Therefore ensure there is at least **150 mm.** of free space above and below the regulator.





MODELS	A	В	С	D	E	F	kg.	ØFixing screw holes
rgf 312	286	201	130	255	181	255	4.0	Ø 6
rgf 320	351	237	181	317	185	320	5.5	Ø 6
rgf 325	351	237	201	317	172	320	8.0	Ø 6
rgf 340	416	318	178	397	275	385	11.0	Ø 6
rgf 360	460	318	228	397	260	410	17.0	Ø 8

Mechanical Dimensions

Table 1

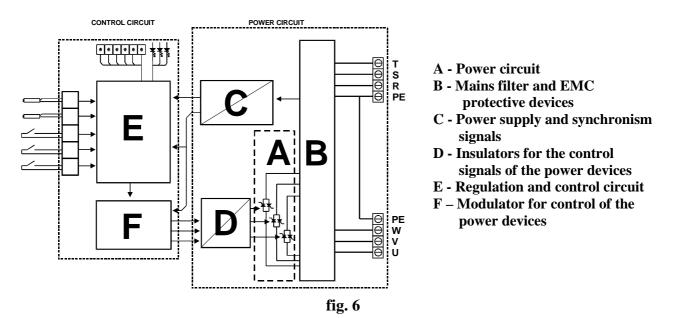
1.3 PRINCIPLE OF OPERATION

The **rgf300** series appliances are voltage regulators that use the phase cutting principle totally controlled over three phases.

The regulators, also referred to as speed controls, have been designed to change the average voltage on the following types of equipment, according to a control signal:

- asynchronous three phase motors connected to **fans, pumps, agitators, mixers**;
- electrical resistor devices with sectioned single / three phase.

Regulation occurs as a result of cutting of the input sinusoid. Regulation does not generate any torque knock or pulsation and is particularly quiet. Any voltage loss is contained within a maximum limit of 1%. Fig. 6 shows a block diagram of regulator rgf300.



The speed regulators are sized to withstand a starting current equal to more than twice the rated current; therefore, when choosing a regulator, it is essential to take into consideration both the motor starting current and the type of motor.

It is actually well-known that, while the starting current in axial fans is equal to 2 or 3 times the rated current, the same current in centrifugal fans can have values around 7 or 8 times the rated current.

As far as the choice of motor is concerned, it is advisable to choose motors suited to the type of regulation. As a general rule, the best suited are:

- motors with high slipping resistive motors
- defluxed motors
- tropicalised motors
- CLASS H motors

as these allow better performance to be obtained with speed changes, they are quieter and start with lower current.

When choosing a motor, it is always advisable to contact your own supplier and order a motor which is suitable for speed control by voltage change. Subsequently, practical trials should be carried out on the motors or prototype machines in order to check their correct operation.

After choosing the motor, the speed regulator must be ordered according to

- the rated voltage,
- **maximum power** required (load-Amperes) bearing in mind the **starting current**.

After the motor characteristics have been checked, the following should be defined in order to identify the type of operating mode and application.

1.3.1 Operating mode

The **rgf** controls allow two different types of operation depending on which type of input is available:

• operation as REGULATOR (also called MASTER)

the phase cutting regulators is directly connected to one or more sensors; the phase cutting is a function of the values selected for:

- **Get-Point P3** (trimmer or centesimal switch)
- **Proportional band P2** (trimmer)

• operation as POWER UNIT (also called SLAVE)

In this case, the **rgf** is set up to be controlled by an external Master regulator which decides the phase cutting of the voltage by sending the control signal to the slave.

The incoming control signal to the **rgf300** regulators can be:

For a MASTER (mA – Vdc)	Active sensors with control in current (mA) or voltage (Ve			
For a MASTER (ohm)	NTC sensors with control in $^{\circ}C/ohm$ (10 kohm @ 25 $^{\circ}C$)			
For a SLAVE (mA – Vdc)	Control signals in current (mA) or voltage (Vdc)			

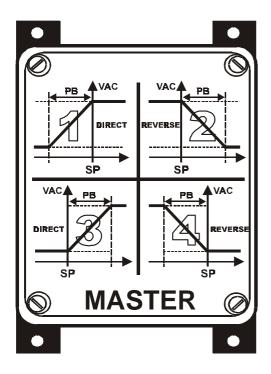
1.3.2 Application

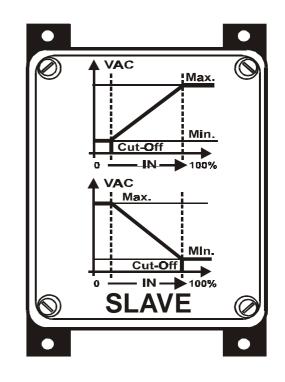
It is generally possible to connect one or two sensors/control signals to all 'MASTER' and 'SLAVE' models; with two (2) sensors-signals connected, the regulator automatically selects the greater or lesser signal.

In the case of active sensors, this can be directly powered (24Vdc / max. 40 mA).

The principal applications are for measuring pressure (**bar**), temperature ($^{\circ}$ C), humidity ($^{\circ}$ RH), delivery (**cu.m/h**), superpressure (**mm.**), static pressure (**Pa**), supertemperature (**destratification**) etc. in plants and machines.

fig. 7





1.4 ELECTRIC MOTORS

Three phase asynchronous motors can be connected to the **rgf300** regulator in applications where the torquemotor speed characteristic is quadratic.

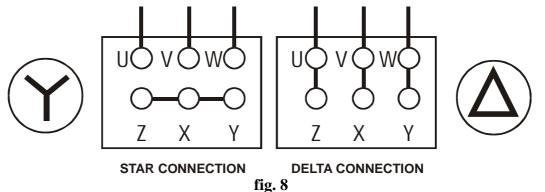
This mainly allows phase cutting application with axial and centrifugal fans used for control purposes.

The correct electrical connection and the supply voltage are given on the motor's specifications plate.

The sense of rotation of the motor can be altered by swapping the connections of two of the three supply cables.

It is important to keep the motor power supply cable as short as possible to reduce the level of interference and leakage currents to a minimum (10 / 15 mt); if the cable has to be long, an auxiliary three-phase filter of exactly the same power as the regulator must be installed on the regulator output.

The figure below shows the star and delta connection configurations.



The **rgf300** regulator can control several motors connected in parallel but the absorption of the motors' total current must never exceed the rated current as given on the **rgf300**'s specification plate.

The speeds of the motors vary at the same time though any differences in behaviour during start up and at low speeds are due to slight differences between the motors even if they are of the same type. However, if the required speeds of the motors are different, motors must be used with different rated speeds. Bear in mind though that motors with very different characteristics create different electrical situations and these may cause problems on start up and at low speeds caused by different resistances of the stators which require different voltages on start up and at low speeds.

1.4.1 Magnetothermal protection

rgf300 devices must be protected by a magnetothermal switch fitted upstream of the cutting regulators. **Installation of magnetothermal protections is the responsibility of the installer**.

It is advisable to fit an automatic magnetothermal protection with a 'C' intervention curve having the following capacity:

RGF 300 models	magnetothermal carrying capacity
rgf 312	20 A
rgf 320	30 A
rgf 325	36 A
rgf 340	60 A
rgf 360	80 A



	Voltage	oltage 420VAC +/- 10 % three-phase (230VAC and 500VAC on request)								
SUPPLY	Frequency			50 Hz (60 Hz						
	Overvoltage	protection			n Category II (4 KV)					
	U	1		RGF 312 12 A up to 50°C environment, over decrease by 0.6 A/°C						
					0 A up to 50°C envir					
CURRENT	Rated									
CURRENT				RGF 340 4	0 A up to 50°C envir	onment, over decrea	se by 1.8 A/°C			
CURRENT POWER OPERATING PRINCIPLE OPERATING CHARACTERISTIC INPUT SIGNALS					0 A up to 50°C envir	onment, over decrea	se by 2.5 A/°C			
	Overload			200% of the 1	rated current (max. 1	0 " every 3 ')	•			
	Control circu	lits		10VA RGF 312 7						
					72 W @ 12A					
POWER					20 W @ 20A					
IOWER	Thermally di	issipated			50 W @ 20A					
					40 W @ 40A					
					60 W @ 60A					
OPERATING				ting, with comp	ensation for inductiv	e loads and motors,	without need for			
PRINCIPLE	connection to	ction to NEUTRAL The output voltage depends on the control signal prevailing between the								
					e at the inputs, whi					
	POWER unit			The action car	ode, according to the	specific appliance r	egulating curve.			
	(Vers. M, V	')				as the input increas	05 OF			
				DIRECT , with the output increasing as the input increases, or REVERSE , with the output decreasing as the input increases.						
OPERATING				Standard Config. : output increasing as the controlled variable increases						
				The output voltage changes to keep set to the target point, selected with						
011111011110110				the Set-Point, the quantity measured by the transducer prevailing						
	D	Regulator (Vers. M, V, X, Y)			between the two available at the inputs, which is chosen by means of the					
	0				pre-established mode (greater or lesser in value).					
	(Vers. M, V				The action mode, either direct or reverse , is chosen in consideration of					
				the controlled quantity, transducer characteristic and load action.						
					Standard: output increasing as the controlled variable increases					
		Vers. M		Two 0-20 mA, Ri = 100 hom analog inputs, priority to the greater std.						
	Control	Vers. V		Two 0-10 Vdc, Ri = 10 khom analog inputs, priority to the greater std.						
		Vers. X, Y		Two kohm analog inputs for the NTC sensors supplied ($10K\Omega$ @						
				25°C), priority to the hottest sensor std.						
SIGNALS	Heat protecti	ion			it, motor protection N					
	Start/Stop	<u> </u>			t : Off Vin=0 = Start					
	Automatic/M				t: Off (Vin=0) =Auto					
	Set-Point 1 /	Set-Point	2		t for Set-point $1/2 \cos \left(\frac{100}{200}\right)$					
	Transducer s	supply		from short cir	(-10% / +20%) 40	mA non-stabilised (surputs, protected			
	Potentiomete	er supply		Two +10Vdc / 5 mA stabilized outputs						
OUTPUT SIGNALS	Auxiliary con			0-10V / 1 mA analog output for cascade control of other SLAVE units						
				NO/NC relay contact, free from potential, for separate or joint signalling						
	RL1 service	relay		of : alarm signals absent / start enabling / voltage supply						
	Version & I	nput		M: 0-20 mA		X: +10/+60°C	Y: -20/+20°C			
	Target value			0 20 mA	0 10 Vdc	+10 +60 °C	-20 +20 °C			
	Proportional			0.4 4 mA 0.3 3.5 Vdc 3 30 °C						
ADJUSTMENTS	Minimum limit / Cut-Off			Adjustable from 0% to 100%						
AND Presettings	Maximum lin				om 100% to 0%					
1 NESEI 111163	Acceleration	Acceleration ramp			Adjustable from 1" to 10"					
	Direct/Reven	Direct/Reverse presetting			Action mode of input prevailing over output : Direct or Reverse					
	Prevailing in	put presett	ing	Selection mode for prevailing input : greater / smaller						
	AC LINE AL	ARM ON	Red	-	d state due to absence	** * *				
LED	T.K. ALARN	4 ON	Red	-	d state due to motor t	*	C contact opening			
	RL1 ONGreen			Signals RL1 service relay energised state						
SIGNALLING	MANUAL M		Yellow		VUAL" operation state					

1.5 rgf 300 TECHNICAL CHARACTERISTICS

				Continually checks presence of the three mains phases; when one phase					
	Mains surveilland	ce		is absent, it stops the appliance and switches on the "phase absent" alarm					
PROTECTIONS CASE INSULATION TEMPERATURE HUMIDITY INSTALLATION ELECTRICAL CONNECTIONS			signal LED (signal LED (AC LINE ALARM)					
	EMC internated			EN 55011 (CEI 110-6) Class	B:				
	EMC integrated	mains inter	ISM applianc	es directly connected to low vo	oltage power mains				
	Overvoltage prot	ection	According to	EN 61000-4-5 : overvoltage C	ategory II (4 KV)				
			RGF 312	286 x 201 x 130 mm	4.0 kg				
CASE INSULATION TEMPERATURE HUMIDITY INSTALLATION ELECTRICAL CONNECTIONS			RGF 320	351 x 237 x 181 mm	5.5 kg				
	Dimensions and	Weight	RGF 325	351 x 237 x 201 mm	8.0 kg				
			RGF 340	416 x 318 x 178 mm	11.0 kg				
			RGF 360	460 x 318 x 220 mm	17.0 kg				
	Materials		GW-Plast 12	0°C and black anodised alumin	nium				
	Degree of protect	ion	IP 55						
	Environmental po	ollution	Strong polluti	on					
	Fire resistance		Category D						
INCLU ATION	Case		Class I (use o	Class I (use of earthed protection cable)					
	Control circuits		4000V between control input and mains voltage components						
TEMPEDATUDE	Working			-20 T 50 (from –20°C to + 50°C)					
IEWIPERATURE	Storing		-30 T 85 (from	-30 T 85 (from –30°C to + 85°C)					
HUMIDITY	RH < 85%								
INSTALLATION	Vertical wall-mo	unting only, wi	ith N° 4 Ø 6 mm	. holes (RGF350 with $N^{\circ} 4 $	8 slotted holes)				
	SIGNAL		Trailing cable	Trailing cable with rated cross section 1.5 sq mm / 22-14 AWG Cu					
		RGF 312	Trailing cable with rated cross section 2.5 sq mm / 20-12 AWG Cu						
ELECTRICAL		RGF 320	Trailing cable with rated cross section 4.0 sq mm/ 24-10 AWG Cu						
CONNECTIONS	POWER	RGF 325	Trailing cable with rated cross section 10 sq mm / 20-6 AWG Cu						
		RGF 340	Trailing cable with rated cross section 10 sq mm / 20-6 AWG Cu						
	RGF 360		Trailing cable	with rated cross section 10 sq	mm / 20-6 AWG Cu				
	89/392/EEC Dire	ective							
		73/23/EEC Directive		CEI-EN 60204-1 : "Safety of machinery"					
	(93/68)								
				EN 50081-2 Generic standard for industrial environment emission					
TECHNICAL			EN 50082-2 Generic standard for industrial environment immunity						
				EN 55011 class B, for radiated disturbance					
STILLDINEDS	89/336/EEC Dire	ective	EN 55011 class B, for conducted disturbance						
	07/000/LLC DI			IEC 801-3) for susceptibility (
				or conducted susceptibility on					
				or fast transients (burst / high-l					
			IEC 801-2 f	or electrostatic discharge (ESE))				

Table 3

2.0 ELECTRICAL CONNECTIONS

2.1 POWER CARD ELECTRICAL CONNECTIONS

For supply and load connection, reference should be made to the diagrams shown in **fig. 8**, making sure the section of the cables is adequate to the connected load.

The power cables (supply and load) must be installed separately from the control cables (analogue inputs and ON-OFF inputs/outputs) keeping the maximum distance possible between the conductors.

Do not place power cables with signal cables in the same raceway. If the cables cross one another, ensure it is at 90° .

ATTENTION : connect the earth conductor to the screw placed purposely beside the dissipator. Use heat resistant cables able to withstand temperatures greater than 90°C.

<u>SURGE ARRESTER</u> : electric protection placed between the regulator supply and the earth to protect the device from transitory mains excess voltage.

<u>ATTENTION</u> : disconnect the PE faston contact from the earth reference, in the 'ELECTRIC STRENGTH TEST'.

The **rgf300** regulators allows connection of three-phase loads *without requiring connection of the NEUTRAL*. This simplifies installation and facilitates the star or delta load configuration.

It is advisable to provide a by-pass switch to allow load activation even when the cutting regulators is faulty (**emergency by-pass**).

When connecting the by-pass, the following precautions should be taken into consideration:

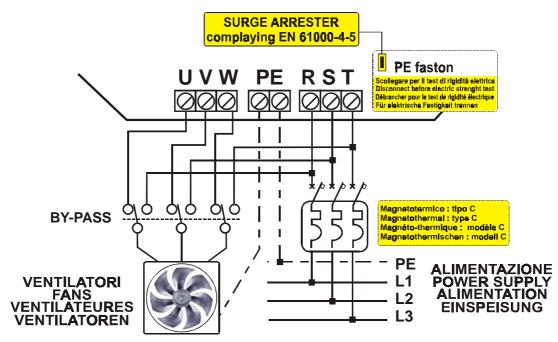
i) connection made through the by-pass switch must keep phase correspondence unaltered so as to avoid destructive shortcircuits and maintain the motor's sense of rotation.

ii) before supplying the load with maximum voltage, supply to the regulator should be disconnected, therefore:

• it is advisable to use a three-position manual switch as a commutation device

• if automatic commutation is carried out by means of contactors, make sure there is some delay (at least 2 seconds) between regulator disconnection and load activation operations.

Electrical connection of the supply and load, for **rgf300** regulators is shown in **fig. 9**





2.2 ELECTRICAL CONNECTIONS, ANALOGUE INPUT SIGNALS

The connections for the control analogue inputs are described below. They can be connected to the **MA** terminal board, in particular:

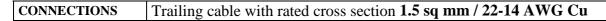
MASTER	version
MASTER	version
SLAVE	version

Active sensors with control in current (mA) or voltage (Vdc) NTC sensors with control in °C (10 kohm @ 25 °C) Control signals in current (mA) or voltage (Vdc)

By connecting the second sensor it is possible to obtain regulation control on the basis of the **GREATER SIGNAL VALUE** (STANDARD version) provided by one of the two sensors.

Warning : when two active type sensors with current or voltage output are connected, use the +V terminal for supply to +22 Vdc / 40mA (MA 3 for IN 1 and MA 7 for IN 2)

There is also a control output available on the terminal board to pilot the **rgf** unit, single phase or three phase, that executes regulation on differentiated loads using the same automatic regulation parameters of the main **rgf300**.



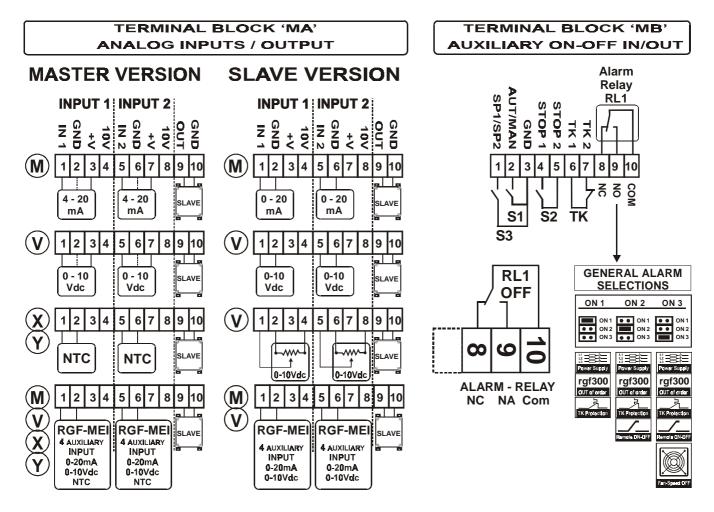


fig. 10

One of the main applications of the **rgf300** series regulators is the control of voltage and speed of rotation of fans. This is modulated to keep temperature or pressure constant as a work point for one or more refrigerating circuits (condensator or evaporator mode).

In the **STANDARD** condition, the fan reaches maximum voltage in output (P4) coinciding with the work **Set-point**. Directions are given below for connection or calibration of **rgf300** regulators with **active pressure sensors**, **NTC** temperature sensors and other possible applications for **direct or remote regulation**.

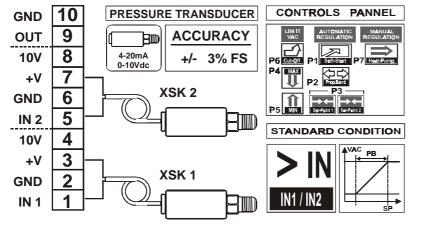
2.2.1 Connection of XSK pressure transducers (4-20 mA)

The table below lists the information necessary for calibration of the **Set-point** (**page 34**) with the position of **P3** referred to the Centesimal Commutators (**Com**.) or Trimmer (**Trim**.), and for calibration of the **Proportional Band** with the position of **P2**.

Set-Po	int Sl	P/P3	for 4-2	20mA, s	Proportional Band PB / P2 setting for					ng for				
SP / P3 Trin	nmer			Cer	ntesimal S	Switch	4	4-20 mA pressure transducers						
[™] [™] [™] [™] [™] [™]		START position	87	$\begin{bmatrix} \mathbf{B} \\ 0 $		r (STA posit					
Setting Trimmer mA		V (*)	0-15 bar	0-25 bar	0-30 bar	N°		Set. Trim	mA	0-15 bar	0-25 bar	0-30 bar		
0 M M	4	0.4	0.00	0.00	0.00	00	m M	m	0.4	0.37	0.62	0.75		
m $\tilde{\Lambda}$	5	0.5	0.93	01.56	01.87	06								
	6	0.6	1.87	03.12	03.75	12	C							
	7	0.7	2.81	04.68	05.62	18								
	8	0.8	3.75	06.25	07.50	25								
	9	0.9	4.69	07.81	09.37	31								
	10	1.0	5.63	09.37	11.25	37								
0 M	11	1.1	6.56	10.94	13.12	44	m M							
<u>m</u> (↓) c	12	1.2	7.50	12.50	15.00	50		с	2.1	1.94	3.28	3.93		
	13	1.3	8.44	14.06	16.87	56	C							
С	14	1.4	9.38	15.63	18.75	62								
	15	1.5	10.31	17.19	20.62	68								
	16	1.6	11.25	18.75	22.50	74								
0 M	17	1.7	12.19	20.31	24.37	80								
	18	1.8	13.13	21.88	26.25	87	m M							
	19	1.9	14.07	23.44	28.12	93								
c M	20	2.0	15.00	25.00	30.00	99	C	Μ	4.0	3.74	6.24	7.50		

Tab. 4

(*) Column V gives the voltage values legible with a multimeter (20Vdc scale limit) on the IN/Gnd terminals of the analogue inputs, corresponding to the mA control signal generated by the 4-20mA transducer in regulation. Fig. 11 shows the connection of two pressure transducers plus the type of operation (standard) and the operating regulation controls.



WARNING :

do not invert the transducer cables (IN / +V) when connection is made to terminals 1/3 and 5/7 as the transducer may be damaged.

<u>ATTENTION</u> : at standard configuration P3/Set-point = max. output fan

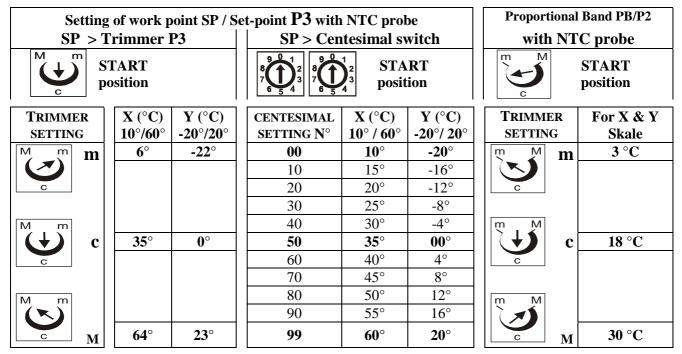
fig. 11

2.2.2 Connection of NTC temperature sensors (10kohm @ 25 °C)

Two versions of NTC temperature sensors are available for rgf300 models:

- X for scale $+10 \degree C$ to $+60 \degree C$
- Y for scale 20 °C to +20 °C

The table below lists the information necessary for calibration of the **Set-point** (**page 34**) with the position of **P3** referred to the centesimal Commutators (**Com**.) or Trimmer (**Trim**.), and for calibration of the **Proportional Band** with the position of **P2**.



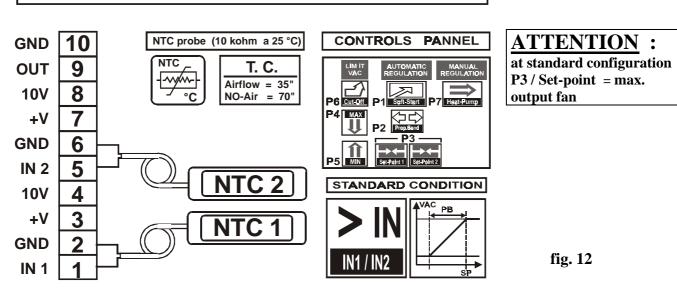
Tab. 5

Connection of the two NTC sensors is shown in **fig. 12** below. Also shown is the type of operation (standard) and operating regulation controls.

Master X for scale +10 C° to +60 C°

Master Y for scale -20 C° to +20 C°

ANALOG INPUTS for NTC PROBE



2.2.3 Connection of other sensors and control signals

Active sensors with : 0-20 / 4-20 mA current output (M vers.), and 0-10 Vdc voltage output (V vers.)

Connection can usually be made to the **rgf300** regulator with one or two active sensors, with current output control signal (0-20 mA) or voltage output (0-10 Vdc) with conductors having two or three wires.

If the sensors have an earth (Gnd) as well as a signal (IN) reference, and they accept a +24Vdc (max. 40 mA supply), they can be directly connected to and supplied by the rgf300 regulator (fig. 13).

The diagram below shows the connection of two differential pressure transducers used to maintain constant pressure / air delivery from a fan in a controlled air flow plant (laminar flow); also shown is the type of operation (standard) and the operating regulation controls.

ANALOG INPUTS for DIFFERENTIAL TRANSDUCER

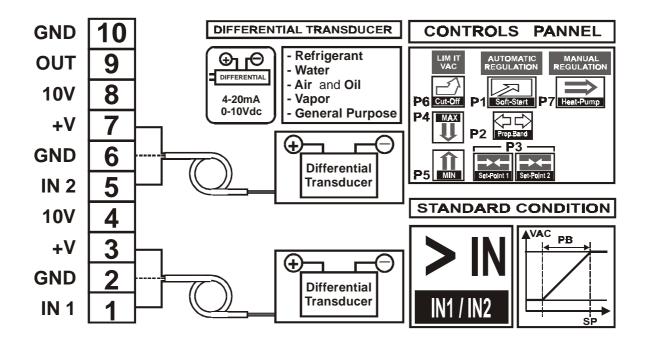


fig. 13

2.2.4 Remote connection for a current (mA) or voltage (Vdc) control signal

Connection of an external control unit (for SLAVE M, V)

If regulator control from an external unit is required, choose one of the following versions:

SLAVE M when the external control unit uses a current control signal (0-20 mA), or **SLAVE** V when the external control unit uses a voltage control signal (0-10 Vdc).

This configuration allows a grid of several regulators to be controlled via a single regulation control signal in either mA or Vdc, even if the regulators are a mixture of single phase and three phase.

It is therefore possible to control totally and automatically several ventilation units and, if necessary, to release one or more regulators from automatic regulation that, using a local manual control signal (only with **0-10 Vdc** control), are regulated to the requested voltage.

The number of inputs available for differentiated control is **2** with priority going to the greater value. See **fig. 14** for the layout of the connections.

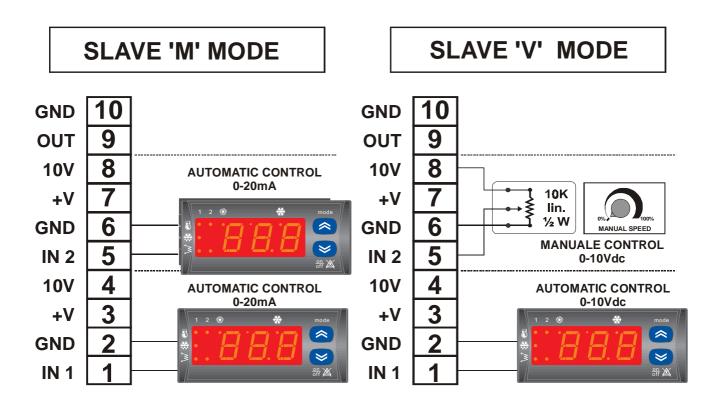


fig. 14

2.2.5 Connection of the rgf MULTIDRIVER control

In this configuration, the **rgf300** regulator is able to guide other single or three phase **rgf** regulators through the **MA 9** (**OUT**) and **MA 10** (**GND**) terminals.

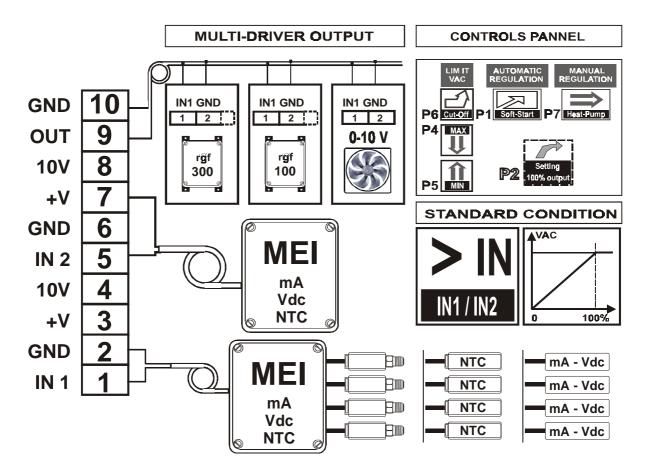
The control output controlled by jumper J6 allows a signal to be sent to several SLAVE (M or V) units.

The signal takes account of the work settings on the main **rgf300**.

Using a single control / sensor, it is therefore possible to control several single or three phase regulation units, that act both simultaneously and proportionally, starting from the transmitted regulation control signals.

Each unit can be used singly with other work limits (MIN and MAX OUTPUT).

The electrical connection and controls available are shown in fig. 15.





Connection of the **rgfMEI** expansion module is also shown in **fig. 15**.

With this module it is also possible to increase the number of sensors (max. 16), which either use current (0-20mA), voltage (0-10Vdc) or kohm (NTC sensor), that can be connected to the regulator.

Four sensors can be connected to this module; the control signal automatically selected is the one with the **greatest value** and as this module is supplied separately.

For more information, consult the user manual for regulator rgfMEI.

2.3 ELECTRICAL CONNECTIONS, ON-OFF INPUTS/OUTPUT

This paragraph describes the connections to the auxiliary S1 - S2 - S3 and TK, ON-OFF inputs / output available on the 'MB' terminal board for which the electrical connection is made with 0-POTENTIAL signal cables.

Also described is the operation of the RL1 ALARM relay and its use based on jumper J14.

CONNECTIONS Trailing cable with rated cross section 1.5 sq mm / 22-14 AWG Cu

2.3.1 Operating selection

The operating selection is obtained by activating the 1/3, 2/3, 4/5 and 6/7 terminals on the 'MB' terminal board.

Fig. 16 shows an example of connection using switches and safety devices. In particular:

S1 indicates a normally open (NO) switch for commutation from AUTOMATIC to MANUAL operation.

S2 indicates a NO contact for activation/inhibition of operation (remote ON-OFF);

S3 represents a NO contact to activate commutation from Set-point 1 to Set-point 2 (SP1 – SP2) N.B. : this control is only operative if the RGFPB10640 optional card is present on the regulator

TK indicates a normally closed (NC) safety device, e.g. a HEAT PROTECTION positioned on the motor, which would halt operation if were open (only if J15=ON2).

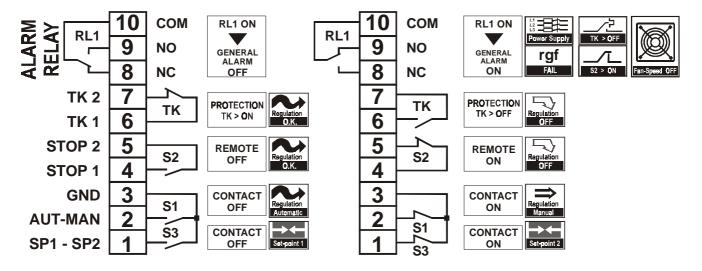


fig. 16

S1: AUT / MAN (MB 2 – MB 3 terminals)

S1 = OPENoperation with variable speed regulation (Led heat-pump = OFF)S1 = CLOSEDMANUAL operation at fixed speed (Led heat-pump = ON)

The S1 contact allows the regulation to be commutated from "AUTOMATIC OPERATION" (power supplied according to the control signal) to "MANUAL OPERATION" with fixed supply power. Activation of this function is displayed by the **heat-pump Led** lighting up.

Application example : WINTER / SUMMER OPERATION of heat pumps.

The fans, connected to the regulator, can be activated depending on the temperature or pressure detected; or, by switching S1=CLOSED, voltage to the fans can be kept constant, equal to the value set with P4 (100% - 0%), for the required time.

CALIBRATION: switch the **S1** contact to **CLOSED** (**Led heat-pump = ON**) and regulate the position of the **P7** trimmer to the desired voltage; then open **S1** (**Led heat-pump = OFF**).

This will reset the automatic speed regulation on the basis of the control signal.

The operation described here can be achieved by means of electromechanical devices. However it is extremely simple if the cutting regulators is controlled by an external regulator (e.g. Energy Light - type **Eliwell**), which can automatically control the **S1** contact.

S2: STOP (MB 4 – MB 5 terminals)

S2 = OPEN	Regulator operational

S2 = CLOSED Operation stop	
----------------------------	--

With S2 = CLOSED operation of the cutting regulators is stopped via a remote contact.

This is useful, for example, to stop fans during defrosting or to link fan operation to activation of a central unit (e.g. compressor) or an alarm (e.g. max./min. temperature).

S3: SP1 / SP2 (MB 1 – MB 3 terminals)

S3 = OPEN	Automatic regulator operation with SET-POINT 1
S3 = CLOSED	Automatic regulator operation with SET-POINT 2

The S3 contact allows the reference Set-point to be commutated from SP1 to SP2.

With S3 = OPEN, the regulator works with **SET-POINT 1**.

With **S3** = CLOSED, the regulator works with **SET-POINT 2**.

Activation of this function is displayed by the SP1 and SP2 Leds lighting up on the optional RGFPB10640 card.

This function is useful, for example, for day / night or winter / summer operations.

Selection is made by means of an external contact in automatic or manual commutation mode.

N.B. : this control is only operative if the optional RGFPB10640 card is present on the regulator.

TK: TK1 – TK2 (MB 6 – MB 7 terminals)

TK = CLOSED	Regular operation (Led TK ALARM = OFF)	
TK = OPEN	Operation stop	(Led TK ALARM = ON)

Intervention of an external safety device opens a 0 V potential contact and halts operation of the regulator. Led TK ALARM (ON) is lighted up.

In plants with fans in parallel, individual protection devices must be used for each motor connected so as to reduce the risk of a total stop.

To restore normal conditions ($\ensuremath{\mathsf{RESET}}$), see the position of jumper J13.

For operation with **J15=2**, the configuration required is :

MB 6/7 = NC

RL1: ALARM relay (MB 8-9-10 terminals) with J14 selection jumper

The **RL1** relay is mounted on the **control card**. The relay has a commutation contact for external signalling of the operating status.

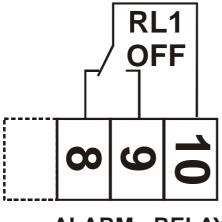
For the operation mode of this output relay, configure jumper **J14** so that all alarms are enabled, as shown in the table below:

J14	RL1	POWER SUPPLY R S T	T.K.	STOP (S2)	FAN SPEED U V W	RGF
ON1	ON	ON	ON	Unable	Unable	O.K.
UNI	OFF	OFF	OFF	Unable	Unable	K.O.
ON2	ON	ON	ON	OFF	Unable	O.K.
	OFF	OFF	OFF	ON	Unable	K.O.
ON3	ON	ON	ON	OFF	ON	O.K.
	OFF	OFF	OFF	ON	OFF	K.O.

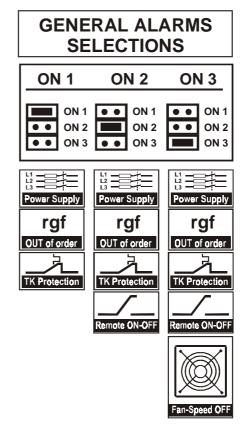
Table 6

Besides relay RL1 in rest conditions, fig. 17 shows the three positions for:

- J 14 : ON1 (standard = factory selection). ON2
 - ON3



ALARM - RELAY NC NA Com



3.0 COMMISSIONING PROCEDURE

Having carried out the electrical connections to the regulator, it is time to perform the configuration, regulation and commissioning operations for the **rgf300** regulator by following the procedure below. It is important to remember that the settings of the **jumpers** (**Jn**) are only to be modified to change the configuration or the operating mode of the regulator set in the factory (check the label on the right side of the

3.1 Jumpers

casing).

This paragraph describes the preset functions of the programming **jumpers**; the jumpers used on the card are of the following types - **2**, **3**, **6** and **10 contacts** (see **fig. 18**).

The term "Jumper" refers to the moveable element which connects two (2) contacts.

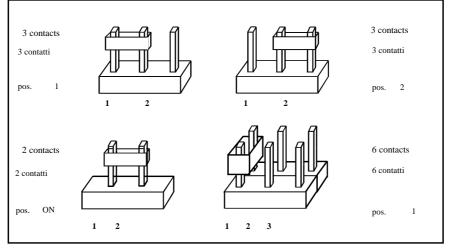


fig. 18

For **2** contact jumpers, the function is activated when the **jumper** is present (position **ON**). For **3** contact jumpers, there are two selection types:

- position '1' i.e. the middle jumper connected to jumper no. 1
- position '2' i.e. the middle jumper connected to jumper no. 2

For 6 contact jumpers (J5 and J14), there are 3 selection types (pos.1, 2, 3); fig. 18 shows position 1. For 10 contact jumpers (J6), there are 5 selection types (pos.1, 2, 3, 4, 5).

The main jumpers on the **rgf300** cutting regulators **control card** are described below.

J1	Selects the work field of the Set-point P3 :	
J1 = ON1	P3 with control from active sensors for 4-20mA or NTC (ohm) sensors for °C	
J1 = ON2	P3 with control from active sensors for 0-10 Vdc	
J2	Activates the standard Set-point or the auxiliary, optional, double digital Set-point : (this control is only operative if the RGFPB10640 card is present on the regulator)	
J2 = ON1	Set-point (P3), with trimmer mounted on the PB 1018/3 basic regulation card	
J2 = ON2	Set-point (P3), with double digital commutators in 99 positions, mounted on the	
	RGFPB10640; it also inhibits operation of P3 (standing) when in the SLAVE configuration, $J2 = ON2$	
J3	Selects the operation of the regulator at the Set-point :	
J3 = ON1	Set-point (P3) corresponds to the minimum control value of the fan	
J3 = ON2	Il Set-point (P3) corresponds to the maximum control value of the fan	
	The standard position is ON2.	

J4	Selects the operating mode of output MA 9/10 in combination with jumper J6.
J5	Selects the work field of the Proportional Band in °C, mA, Vdc :
J5 = ON1	P2 scale for control input with NTC (ohm) sensors for $^{\circ}$ C (range 3 – 30 $^{\circ}$ C)
J5 = ON2	P2 scale for control input with active sensors from 4-20 mA (range 0.4 – 4 mA)
J5 = ON3	P2 scale for control input with active sensors from 0-10 Vdc (range 0.3 – 3.5 Vdc)
J6 J6 = ON1	Selects the type of output control signal from the rgf300 on terminal MA 9/10 : 0-10 V signal proportional to the power output (for $J4 = 2$)
$\mathbf{J6} = \mathbf{ON2}$	10-0 V signal proportional to the power output (for $J4 = 1$)
$\mathbf{J6}=\mathbf{ON3}$	Control signal with OFFSET (for $J4 = 1$)
$\mathbf{J6}=\mathbf{ON4}$	Signal to indicate the shift of the input signal from the Set-point (for $J4 = 1$)
J6 = ON5	Input signal (greater or lesser)(for $J4 = 1$)
J 7	Selects the size of the value in % C (of control) to display on the portable unit:
J7 = ON1	displays control signal %C with OFFSET
J7 = ON2	displays control signal %C without OFFSET (0 – 100%)
J8 = ON	Selection for 'DIRECT' operation with $J3 = ON1$ If J 8 is ON, the voltage supplied to the fans increases with the increase in input signal. Selection for 'REVERSE ' operation with $J3 = ON2$ If J 8 is ON, the voltage supplied to the fans increases with the decrease in input signal.
J9 = ON	 Selection for 'REVERSE ' operation with J3 = ON1 If J 9 is ON, the voltage supplied to the fans increases with the decrease in input signal. Selection for 'DIRECT' operation with J3 = ON2 If J 9 is ON, the voltage supplied to the fans increases with the increase in input signal. The selection of one excludes the other. In the versions with NTC sensor, the operation of J8 and J9 with J3 ON1/ON2, is inverted.
J10	Selects the MASTER or SLAVE operating mode:
J10 = ON1	selects SLAVE mode for the rgf300
J10 = ON2	selects MASTER mode for the rgf300
J11	Selects the input signal priority:
J11 = ON1	selects the LESSER value
J11 = ON2	selects the GREATER value
	• In the version with NTC sensor, selecting J11=ON1 is the equivalent of selecting the sensor with the greater °C value
J12	Selects the type of input for use of the portable unit :
J12 = ON1	displays the voltage signal in V (0-10 Vdc)
J12 = ON2	displays the current signal in mA (0-20 and 4-20 mA)
	• In the version with NTC sensor, selecting J12=ON1 is equivalent to automatic setting of the work field of the sensor ($X = +10$ to $+60$ °C and $Y = -20$ to $+20$ °C)

J13 J13 = ON1 J13 = ON2	Selects the RESET operating mode of the TK contact (terminal board MB 6/7): when selected, if the TK protection intervenes, the regulator must be switched off and on again to reset the system after the cause has been eliminated (MANUAL RESET). when selected, if the TK protection intervenes, the system restarts automatically after the contact has been reset (AUTOMATIC RESET).
	The standard position is ON2.
J14	Selects the operation of the RL1 relay:
J14 = ON 1 J14 = ON 2	when selected the relay is active (position ON), in the absence of alarms (Alarm Led = OFF) when selected the relay is active (position ON), in the absence of alarms (Alarm Led = OFF) and with open remote STOP control signal
J14 = ON 3	when selected the relay is active (position ON), in the absence of alarms (Alarm Led = OFF), with open remote STOP control signal and with supply of voltage to the load in course. The standard position is ON3 .
J15	Selects the operation of the heat protection:
J15 = ON 1 J15 = ON 2	when selected, the TK heat protection contact is excluded. when selected, the TK heat protection contact must be connected to the terminal board The standard position is ON1 .
J16	Selects the type of input on the IN 1 channel:
J16 = ON 1 J16 = ON 2	when selected, the input is activated for control signals in mA . when selected, the input is activated for control signals in Vdc and ohms (NTC sensor)
J17 J17 = ON 1 J17 = ON 2	Selects the type of input on the IN 2 channel: when selected, the input is activated for control signals in mA . when selected, the input is activated for control signals in Vdc and ohms (NTC sensor)

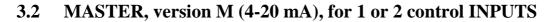
WARNING !

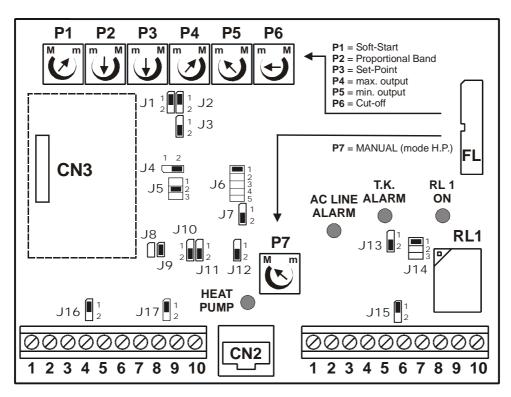
• Check the position of jumpers 'Jn' during commissioning. If the rgf300regulator work mode is altered (MASTER / SLAVE), refer to fig.s 19, 20, 21, 22 and 23 which give the standard work configurations of the jumpers.

• The regulator is already set for the operations indicated on the label on the side of the casing; if modifications are required, describe and indicate the modifications made on the TECHNICAL ASSISTANCE MODULE.

WARNING !

• The configuration with NTC temperature sensors is not compatible with other configurations. It is not therefore possible to alter the position of the jumpers to pass from operation with NTC sensors to operation with active sensors or control signals in mA or Vdc, nor to change the °C work field/scale of the rgf regulator.







3.3 MASTER, version V (0-10 Vdc), for 1 or 2 control INPUTS

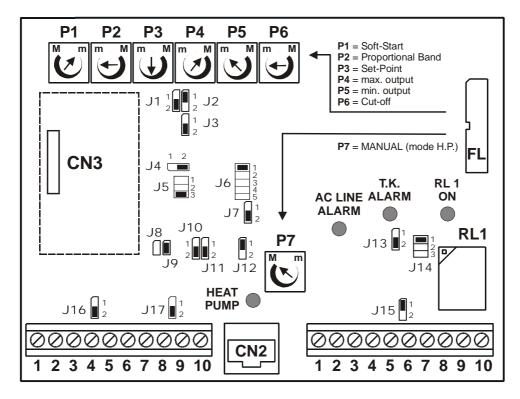
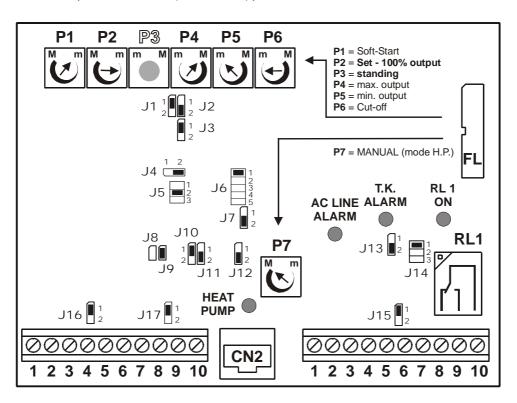


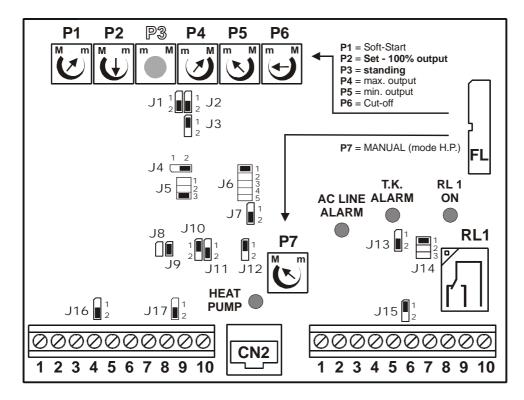
fig. 20



3.4 SLAVE, version M (0-20 mA), for 1 or 2 control INPUTS

fig. 21

3.5 SLAVE, version V (0-10 Vdc), for 1 or 2 control INPUTS



3.6 MASTER, version X or Y (NTC °C), for 1 or 2 control INPUTS

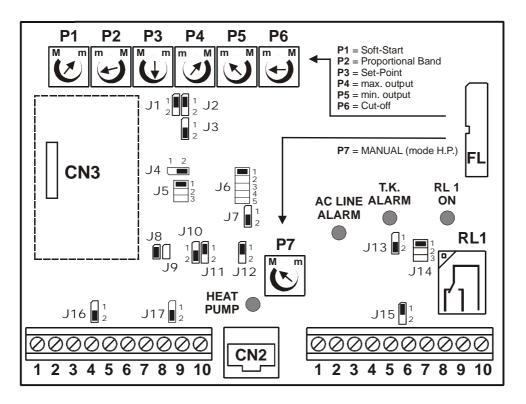


fig. 23

The rgf300 version for temperature control inputs with NTC sensors is available in two °C scales:

MASTER X with temperature scale +10 to +60 °C

MASTER Y with temperature scale -20 to +20 °C.

The scale limit values for the Trimmer with **P3** Set-point calibration are inverted compared to the current (**mA**) and voltage (**Vdc**) scales for the active sensors.

WARNING !

• The configuration with NTC temperature sensors is not compatible with other configurations. It is not therefore possible to alter the position of the jumpers to pass from operation with NTC sensors to operation with active sensors or control signals in mA or Vdc, nor to change the °C work field/scale of the rgf regulator.

3.7 Optional module for dual Set-point configuration (SP1 – SP2)

The **rgf300** regulator can be used in versions **MASTER M**, **V**, **X**, **Y** with a **reference dual Set-point** by using the **optional** module card **RGFPB10640** for double control Set-points.

Insert the card in the CN3 connector on the rgf300 regulator (see the position in fig. 25).

When the card is positioned, with J2=ON2, Trimmer P3 is disabled (standing) and substituted by two pairs 99 position digital commutators.

Activating the contact on terminal board **MB 1/3**, it is possible to change the regulator's work point. The commutation is shown by the lighting up of the **SP1** and **SP2 Leds** on the card above the centesimal commutator for setting of the Set-points.

Fig. 26 shows the RGFPB10640 card and the reference table for inputs in:

mA (bar/°C for pressure transducers) and °C (for NTC sensors) in the different work ranges.

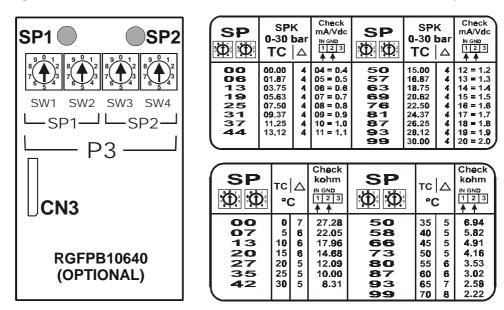


fig. 24

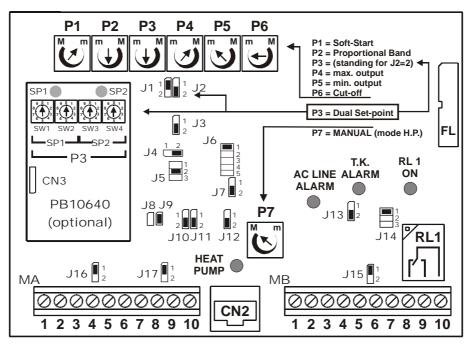


fig. 25

4.0 CONTROL TRIMMER

WARNING : Before starting the regulator calibration phase, check the position of the trimmers as shown in figs. 26 and 27.

The position of the trimmers marked with a spot of red paint (factory calibrated trimmers) must not be altered.

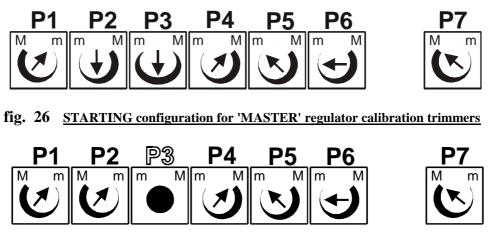


fig. 27 STARTING configuration for 'SLAVE' regulator calibration trimmers

The work parameters regulation can be divided into **TWO PHASES**:

- 1. definition of regulator work limits: the values of P4 and P5/P6 are defined in this phase.
- 2. definition of regulator work field: the values of P2 and P3 are defined in this phase.

With **SLAVE** type regulators, the regulator calibration is completed during **PHASE 1**. With **MASTER** type regulators, **PHASE 1** is necessarily followed by **PHASE 2** which defines the **Work Range** and **Set-point**.

N.B.: it is possible to read the work parameters by connecting the **HELP1** portable display unit; press the keys as shown in **fig. 28** to display the readout of the value set with the calibration trimmers.

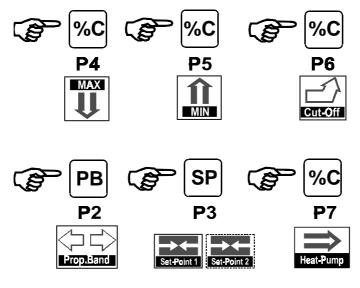
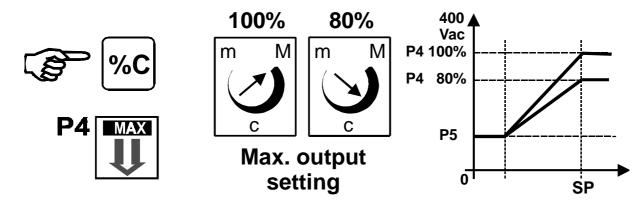


fig. 28

4.1 MAX. OUTPUT regulation (P4 trimmer) - PHASE 1



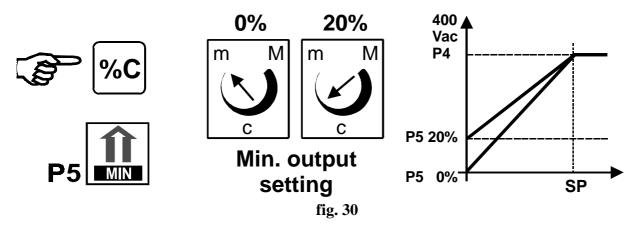


P4	Limits the maximum operating voltage (from 100% to 0%).
MAX.OUTPUT M = 100% m = 0%	It is useful for limiting the maximum capacity or noise of the fan when turning at max. speed. It is set in the factory to the max. value ' M ' which corresponds to the max. voltage supplied to the fan and equal to 100% of the control value.

To regulate the MAX. OUTPUT voltage correctly, proceed as follows:

- 1) bring the P5 trimmer (manual control of minimum voltage) to position 'M';
- 2) turn the P4 trimmer starting from position 'M' as far as the desired MAX. voltage value;
- 3) bring the P5 trimmer to minimum value 'm': the output voltage to the load will have the P4 value as MAX.

4.2 MIN. OUTPUT regulation (P5 trimmer) - PHASE 1



P5	Allows manual regulation of the minimum output voltage from 0 to 100%.
MIN.OUTPUT m = 0% M = 100%	During the calibration starting phase, it is used to check the regulator for correct cutting regulators and the fans for correct rotation. It is also used as reference for CUT-OFF calibration (P6) and calibration of the max. output voltage (P4).

Regulation of trimmer **P5** supplies the fan with a constant minimum voltage when the automatic control is not working or the control input is disconnected.

Rotate P5 anticlockwise starting from position 'm' until the desired minimum voltage is reached.

4.3 CUT-OFF regulation (P6 trimmer) - PHASE 1

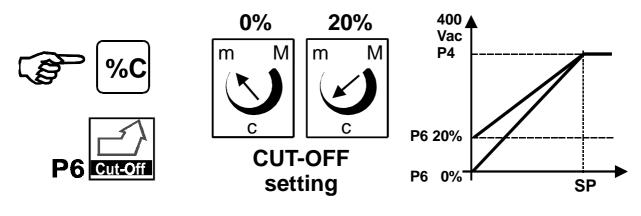


fig. 31

P6		
CU	Т-()FF
m	=	0%
Μ	=	90%

Adjusts the minimum voltage being supplied to the fan during automatic operation: the fan will not be supplied with voltage lower than the predetermined value; this avoids the supply of minimum voltage which would not be sufficient to provide a starting torque for the fan rotation.

In order to adjust the 'CUT-OFF' correctly, proceed as follows:

1) turn the **P5** trimmer (manual speed control) starting from position '**m**' until the desired minimum rotation voltage is obtained;

2) turn the P6 trimmer starting from position 'm' until the P6 value overlaps the P5 value;

fix the P6 trimmer position exactly and check the state of the RL1 ON Led which must move from the 'off' position to the 'on' position (only if J14 = ON3);

3) bring the P5 trimmer to minimum value 'm': the load will now be supplied starting from the minimum voltage selected.

4.4 PROPORTIONAL BAND regulation (P2 trimmer) - PHASE 2

P2
PROPORTIONAL
Band
- mA
- Vdc
- °C

Trimmer P2 takes on different roles depending on the model of rgf300 chosen:
on 'Master' operation models (M,V,X,Y), P2 adjusts the proportional band.
on 'Slave' operation models (M and V), trimmer P2 is set at the factory to give maximum voltage to the load corresponding to the maximum control signal sent to the regulator.

4.4.1 Versions with MASTER regulator operation

In **MASTER** regulator versions the range determines the value in **mA / V / °C** of the input signal that, once set, passes the fan from the maximum voltage (**MAX.OUT P4**) to the minimum set (**MIN. OUT P5** or **P6**).

The P2 work field is different for different versions.

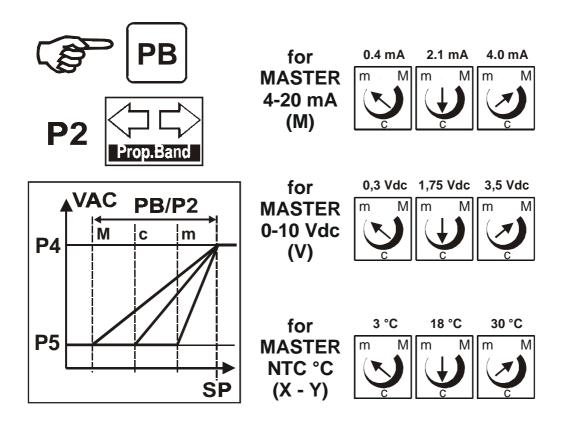


fig. 32

Version M for 4/20 mA active sensors:

ranges from:	-	0.4 mA	(trimmer in position ' m ')
	-	2.1 mA	(trimmer in position 'c')
	-	4.0 mA	(trimmer in position ' \mathbf{M} ').

The current signal is tied to the scale amplitude of the transducer used.

In the case of pressure control (which occurs most frequently), the value of the **mA/Bar** ratio changes depending on the pressure transmitter scale.

Version V for 0/10 Vdc active sensors:

ranges from:	-	0.30 Vdc	(trimmer in position ' m ')
	-	1.75 Vdc	(trimmer in position 'c')
	-	3.50 Vdc	(trimmer in position ' \mathbf{M} ').

For Vdc / set physical quantity correspondence, refer to the characteristics of the sensor used.

Versions X and Y for NTC sensors (°C) :

ranges from:	-	3.0 °C	(trimmer in position 'm')
	-	18.0 °C	(trimmer in position 'c')
	-	30.0 °C	(trimmer in position ' \mathbf{M} ').

4.4.2 Versions with SLAVE regulator operation

In this case, the **rgf300** is subjected to a control signal (automatic or manual) generated by a remote controller.

Trimmer P2 only determines the maximum voltage supplied to the fan corresponding to the maximum control signal received by the regulator from the remote controller:

20 mA for the SLAVE M version, and

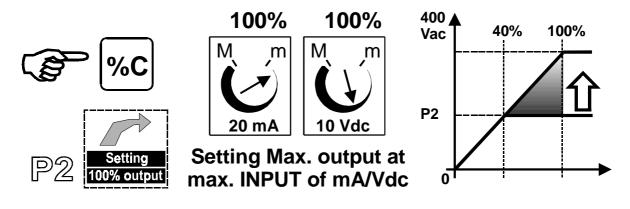
10 Vdc for the SLAVE V version.

Starting with the trimmer in position 'm' and remote control at maximum (20 mA or 10 Vdc), check the value of the voltage supplied to the load.

It is at maximum (100%) when the trimmer is roughly in the position shown in **fig. 33** with the control signal in mA and Vdc.

In this configuration, the **DIRECT** or **REVERSE** mode is determined by the external controller.

N.B.: in the SLAVE configuration the P2 trimmer is already calibrated and varnished to hold its position in the factory and must NOT be altered.





4.5 SET-POINT regulation (models M, V, X, Y) P3 trimmer - PHASE 2

P3	It is possible to activate the SET-POINT (the automatic regulation start point) by activating the P3 trimmer.		
SET POINT	In the standard configuration, the Set-Point coincides with the maximum value of supply (100% or value of P4 max. output).		
	The regulation scales are as follows in 'Master' versions:		
- mA	• model \mathbf{M} : from $0 \mathbf{m} \mathbf{A}$ to $20 \mathbf{m} \mathbf{A}$		
- Vdc	• model V : from 0 Vdc to 10 Vdc		
- °C	• model X : from 10 °C to 60 °C		
	• model Y : from -20 $^{\circ}$ C to 20 $^{\circ}$ C		
	The direction of regulation goes from 'm' (low values) to 'M' (high values).		
	In SLAVE versions (M and V), this trimmer is not operative (STANDING) even if present.		
	Note:		
	- for M versions, the regulation refers to the current control signal (mA)		
	- for V versions, the regulation refers to the voltage control signal (Vdc).		
	- for X and Y versions, the trimmer regulation refers directly to the temperature in °C.		
	It is therefore necessary to change the " range " of the sensor being used to work out the corresponding measured quantity / control signal.		

Fig. 34 shows the values and positions of the trimmers for the different 'MASTER' configurations.

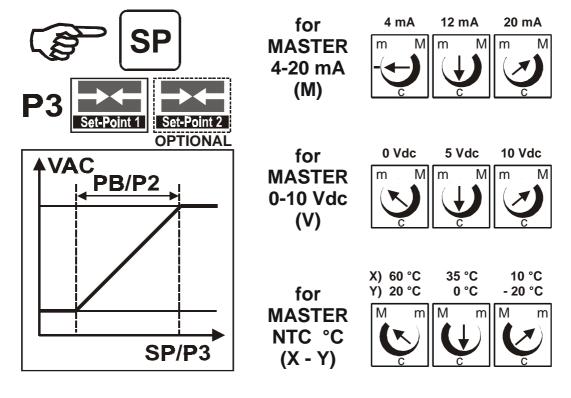


fig. 34

During the calibration procedure, it is advisable to start from position 'c' so as to be positioned halfway through the work field and the connected transducer or sensor scale.

4.5.1 Centesimal SET-POINT option (mod. M, V, X, Y) P3 - FHASE 2

In the MASTER configuration, the **RGF300** can be chosen with the **RGFPB1064 OPTION**. This plug support the **SIMPLY Set-point** (**P3**), with double digital commutators for **DUAL** Set-Point (**S3** switch) in **99** setting positions.

So it's possible to set two (2) working Set-point (ex.: Night / Day – Winter / Summer, etc.) with S3 switch (led SP1 / SP2 switch-on)

P3	It is possible to activate the SET-POINT (the automatic regulation start point) by activating the P3 centesimal switch (100 positions).		
CENTESIMAL & DUAL	In the standard configuration, the Set-Point coincides with the maximum value of supply (100% or value of P4 max. output).		
SET POINT - mA (Vdc) - °C	The regulation scales are as follows in 'Master' versions: • model M : from 4 mA to 20 mA • model V : from 0 Vdc to 10 Vdc • model X : from 10 °C to 60 °C • model Y : from -20 °C to 20 °C The direction of regulation goes from '00' (low values) to '99' (high values).		
	 In SLAVE versions (M and V), this trimmer <u>is not operative (STANDING)</u>, even if present. Note: for M versions, the regulation refers to the current control signal (mA) for V versions, the regulation refers to the voltage control signal (Vdc). for X and Y versions, the trimmer regulation refers directly to the temperature in °C. It is therefore necessary to change the "range" of the sensor being used to work out the corresponding measured quantity / control signal. 		

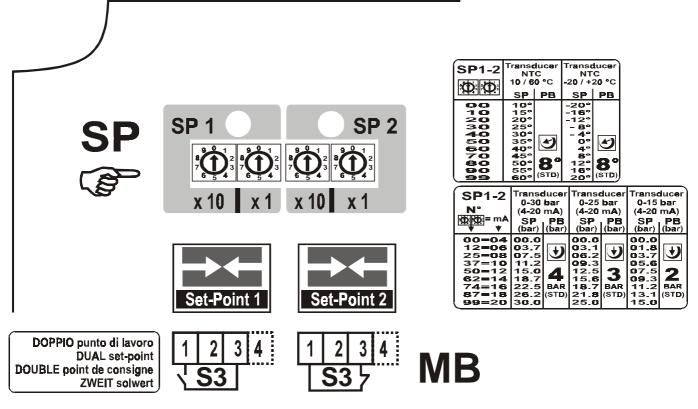
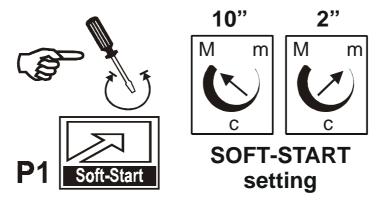


fig. 36

4.6 SOFT-START regulation (P1 trimmer)

P1	Adjusts the rapidity with which the fan speed varies ('slow start' and 'slow stop'); in
Soft-Start	practice it makes the system 'slow' or 'fast' depending on the change in the automatic control signal.
	In the 'M' position (trimmer completely turned clockwise), the variation speed is slowed to
m = 2"	the maximum (system slow to vary).
$\mathbf{M} = \mathbf{10''}$	In the 'm' position (minimum), speed variation is almost instantaneous ('fast' system).
	The cutting regulators is provided with a minimum Soft-Start time equal to circa 2 seconds
	$(\mathbf{P1=m})$ to avoid possible hunting that might be caused by an excessively slow system.





4.7 MANUAL regulation (P7 trimmer)

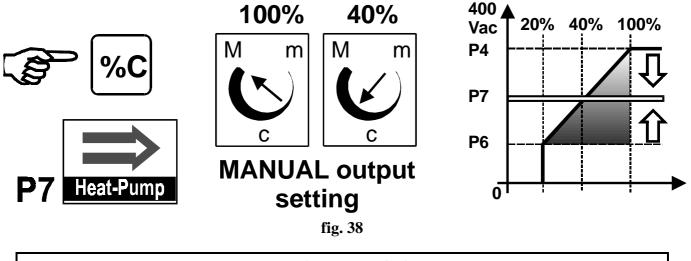
P7 MA	NUAL
m =	0% (o P6)
M =	100%

Adjusts the operating speed in MANUAL mode:

it allows a constant output voltage value to be set from between 100% and the CUT-OFF (P6), value using trimmer P7.

Once S1 is closed with a '0 V ' potential contact, turn P7 anticlockwise starting from position M until the desired voltage value is reached. The standard preset position for P7 is 'M'

The standard preset position for $\mathbf{P7}$ is ' $\mathbf{M'}$.



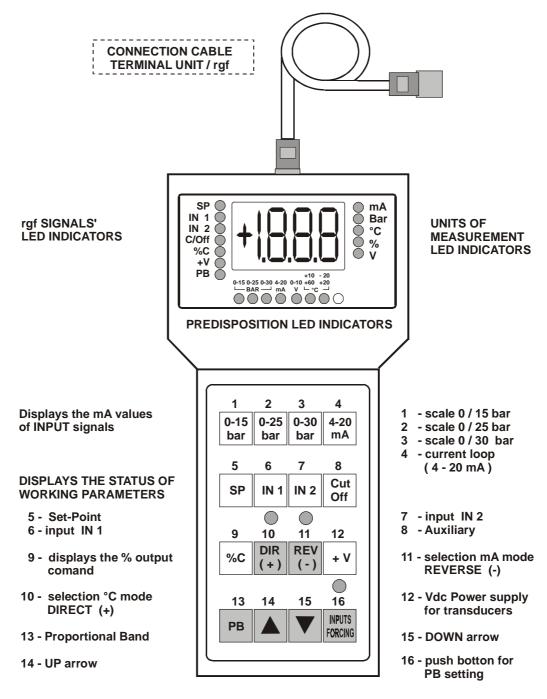
WARNING !

The position of trimmers marked with a spot of red paint (factory calibration) must not be altered

5.0 HELPI 10: PORTABLE DISPLAY UNIT

All calibration operations described can easily be carried out with the portable module called **HELPI10** for display of work parameters.

All three phase regulators in the **rgf300** series are fitted with the **CN2** connector located between the **MA** and **MB** terminal boards. After connecting the **HELP110** module, the settings made with the regulator work parameter trimmers can be chosen and displayed, even if the **rgf300** is being supplied on the workbench. The portable **HELP110** unit is shown in **fig. 39** with function keys described.



(*) 10/11/13/14/15/16 - push bottons for Proportional Band setting (PB)

SUMMARY TABLES FOR USE OF THE HELPI10 DISPLAY MODULE.

Supply voltage	22 V (1836 V)	22 V (1836 V) From the connected appliance		
Input	4 - 20 mA	Can be changed via the keyboard to:	0 - 15 bar 0 - 25 bar 0 - 30 bar	
Layouts	0 - 10V			
	NTC +10+60°C]		
	NTC -20+20°C			
	Main Set-point	Units of measurement	mA,V,bar,°C	
	Transducer input 1	"	mA,V,bar,°C	
Signala magazina d	Transducer input 2	"	mA,V,bar,°C	
Signals measured	% output control signal	"	% (0100)	
	Transducer supply voltage	"	V	
	Proportional band	"	mA,V,bar,°C	
Dimensions	225 x 105 x 40 mm.			
Weight	0.5 kg			

Technical characteristics

Screen

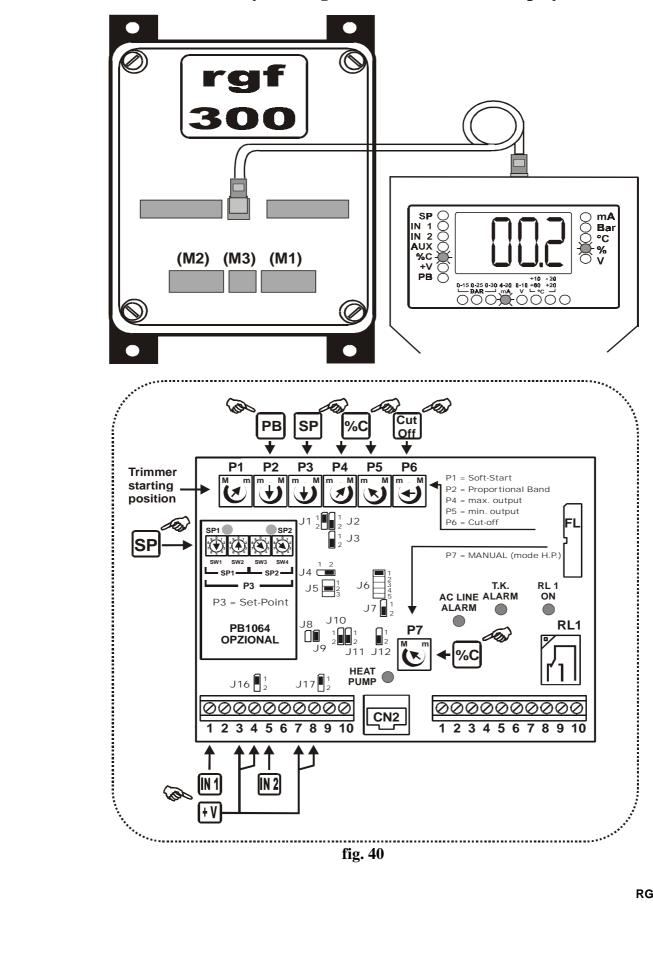
NUMERIC DISPLAY	LCD 3 ¹ / ₂ digit		
	position	left of the display	
LED unit	no.	7	
Selected input	colour	green	
	function	indicates which signal is being displayed at any moment	
	position	below the display	
	no.	8	
Led unit	colour	red	
Regulator set-up	function	 indicate the set-up on the connected regulator, including units of measurement and scale limits, for the following signals: SP, IN1, IN2. Also indicates if the scale factor has been modifed from mA to bar 	
	position	right of the display	
Led unit	no.	5	
Units of measurement	colour	green	
	function	indicate the units of measurement of the value on the display	

Led

Caption	Function
DIR (+)	Direct operation selected for calibration of the proportional band
REV(-)	Inverse operation selected for calibration of the proportional band
Inputs Forcing	Forced transducer inputs for calibration of the proportional band

COMMISIONING PROCEDURE :

Function keys > **Regulation** (**Trimmer**) > **Displays**



How to use the HELP110 display module

•	Connect the HELPI10	unit to the regulator to calibrate using the supplied cable; this can be done with the
		nd operating but without transducers or sensors connected
•		onding to the input set-up of the regulator are lit up correctly.
•	If desired, for 4-20 mA	inputs, choose the scale in bar corresponding to the pressure transducer used. There are
	three choices:	
	Transducers with range	
	Transducers with range	0 - 25 bar press key 2 : 0 - 25 bar
	Transducers with range	
•	Set-point	Press key 5 "SP": the "SP" Led of the selected input and the Led of the unit of
		measurement (mA , bar , ° C , V) corresponding to the regulator input set-up will light up.
		The current value of the Set-point will be displayed.
		To alter it, adjust the P3 adjustment trimmer.
•	Input 1	Press key 6 "IN 1": the "In 1" Led of transducer input 1 and the Led of the unit of
		measurement (mA , bar , ° C , V) corresponding to the regulator input set-up will light up.
		The current value of the N1 transducer input will be displayed.
•	Input 2	Press key 7 "IN 2": the "In 2" Led of transducer input 2 and the Led of the unit of
		measurement (mA , bar , ° C , V) corresponding to the regulator input set-up will light up.
		The current value of the N 2 transducer input will be displayed.
•	Cut-Off	(N.B: Only for regulators with PB1018/4 control card)
		Press key 8 "Cut-Off": the "%C" Led of the selected input and the Led of the unit of
		measurement"%" will light up.
		To check the regulator for correct cutting and the fans for correct rotation, adjust the
		corresponding trimmer P6, and see the current value on the display
•	Cutting percentage	Press key 9 "%C" : the "%C" Led of the selected input and the Led of the unit of
		measurement"%" will light up.
		The current value of the cutting percentage of voltage supplied by the regulator will be
		displayed (P4, P5, P7 trimmer set-up).
•	Transducer power	Press key 12 "+V" : the "+V" Led of the selected input and the Led of the unit of
	supply	measurement "V " will light up.
		The value of the supply voltage for transducers connected to the service will be
		displayed at circa +22 V rated (refer to the user manual of the connected regulator for
		details of the connection to the terminal board).
•	Proportional	Press key 13 "PB": the "PB" Led of the selected input and the Led of the unit of
	Band	measurement (mA, bar, °C, V) corresponding to the regulator input set-up will be
		displayed.
		The last value of the Proportional Band (PB) set will be displayed, differing for each
		type of input signal (mA, Vdc, bar, °C); modifiable using arrow keys 14 and 15 (see the
		limits shown on fig. 32).
		To increase : press key 14 " UP " (up arrow).
		decrease : press key 15 "DOWN" (down arrow).
	(*) calibration	(*) without connecting the sensors to inputs IN1 and IN2 :
		• Press key 13
		• Set the desired PB value, using keys 14 & 15
		• Choose the operating mode of the regulator by pressing either DIR or REV .
		• Press key 16 " Inputs Forcing": the corresponding yellow Led will light up.
		• Adjust the regulation trimmer of the P2 band to read the "50.0 (%)".
		• Press key 16 again: the yellow Led will go out and the regulator will now
		work with PB legible from key 13 .
N.R	. : the value of PR in m A	bar , Vdc, °C read on the HELPI unit is always the last one set and different for the type
ot ii	ncoming signal (mA, Vd	2, bar, °C)

For more information, consult the user manual for **HELPI 10 display module**.

6.0 rgf 300 EASY REFERENCE COMMISSIONING GUIDE

Having connected the supply and load to the regulator, the control system commissioning operation must be divided into two phases in order to separate the **definition** of the regulator **work voltage limits** (**P4-P5-P6**) from the **surround control values** (**P3-P2** with mA - Vdc - °C) in automatic regulation:

QUESTION	ANSWER	HOW TO PROCEED
Should the fan reach 100 % speed in automatic regulation?	• NO	• With P5 in position M , turn P4 clockwise slowly starting from
(P4)	• YES	'M' until the desired max. voltage is reached.Turn P4 to position 'M'
Should the fan constantly rotate at a fixed speed regardless of the	• YES	• Starting from 'm', turn P5 slowly anticlockwise until
automatic regulation signal?	• NO	reaching the desired voltageTurn P5 to position 'm'
(P5) The fea starts rotating at 100 VAC		*
The fan starts rotating at 100 VAC . How can you find this CUT-OFF		Having found the correct value with P5 , starting from 'm', turn P6
(rotation start) value?	voltage value that turns the fan	
	slowly	supply STOP threshold (Led
(P6)	(e.g.: 100VAC)	RL1=OFF with J14=3) so as to
		overlay it on the P5 value.

Once the **P4**, **P5** and **P6** values have been defined and therefore become fixed reference parameters, define the work field values (**P2** Proportional Band) and work point value (**P3** Set-point) in the:

"MASTER" CONFIGURATION with control in mA / Vdc / $^{\circ}\mathrm{C}$

P3, point where the system reaches maximum supply to the load, starting from MIN.OUT or CUT-OFF

P2, point where the system reaches the MIN.OUT control value for the fans

How can you determine the proportional band? (P2)	Use the P2 trimmer. First, check the trimmer's work parameters (fig. 32).	Starting from position 'm', turn P2 anticlockwise until the position considered as the optimum regulation is reached.
How can you determine the Set- Point? (P3)		Starting from position 'c', turn P3 clockwise or anticlockwise until the position considered as the optimum regulation is reached.

Once P2 and P3 have been positioned, check the modulation system and slowly correct by using:

P3 (+/-) if the Set-point is not working at the required pressure or temperature, and with **P2** (+/-) if the fan voltage variation is too fast or too slow.

"SLAVE" CONFIGURATION with control in mA / Vdc

With this configuration, once the **P4**, **P5** and **P6** reference parameters have been defined, the regulator carries out speed changes on the basis of the control values which are transmitted by the external controller, without needing further calibration.

In the case where you wish to change from **MASTER** to **SLAVE** configuration and therefore reprogram the type of regulator control, you should check the layout of the configuration jumpers shown and adjust the value of **P2** which determines **100%** of the fan control.

QUESTION ANSWER HOW TO PROCEED			
	QUESTION	ANSWER	HOW TO PROCEED

What should you do to change from	First, check the jumper layout (fig.	Generate the maximum control
the MASTER to SLAVE	19 > 21 (for M) & fig. 20 > 22 for	value (20mA or 10Vdc) and,
configuration?	V).	starting from position 'm', turn P2
only from MASTER M and V to:	Then calibrate the scale limit value clockwise until 400 VAC ca	
- SLAVE M for 0-20mA	(100% of the supply to the fan)	read on the output terminals.
- SLAVE V for 0-10 Vdc	when the control value is at 10Vdc	
	or 20mA	

• Note : for versions X and Y, with NTC sensor, no changes can be made in regard to: - configuration (from NTC to mA or Vdc control)

- temperature scale (from version X to version Y and viceversa).

In this case too, all calibration operations described can be easily carried out using the **HELPI** portable work parameter display module that allows the operator to see and set values with the calibration trimmers even if the rgf300 is being supplied on the workbench

7.0 TROUBLE SHOOTING

Some of the problems which may occur during or after unit commissioning are listed below with their possible solutions.

Problem	Cause	Solution
Unit supplied but load does not activate.		S1 . Check supply connections and input
	AC LINE on).	phases.
	C2. The load is not connected.	S2. Check there are no electrical
		interruptions between regulator and
	C3. No control signal.	load. S3 . Check sensors for correct operation
	C3. No control signal.	(return voltage) and connections to
		terminal board MA .
		S4 . Check P3 trimmer calibration and
	C4. Incorrect operating mode (direct,	positions of jumpers J8/J9, J2/J3,
	reverse) and Set - points not adequate	J10/J11/J12.
	for signal control.	S5 . Check P4 trimmer calibration.
	C5 . Maximum voltage supplied to lower	
	load at minimum starting voltage.	S6. Check STOPS 4, 5 control contact
	C6. Remote STOP (ON-OFF) (MB 4,	on MB terminal board.
Tradition is to see the set of the tradition to	5 contacts closed).	61 C1 1 1 1 1
Tension can be read on outlet terminal heads to load (circa 370 VAC) but	C1 . Load not connected to regulator terminals.	S1 . Check electromagnetic switch or motor / regulator connection sectioner.
motor does not start.	terminais.	S2 . Check the motor heat protection.
Cutting regulators supplies voltage to	C1. Minimum voltage supplied to load	S1 . Check P6 trimmer calibration.
the load but load does not activate.	is lower than needed for starting.	51. Check I & unmiler curroration.
Protection fuses burn out.	C1. Regulator undersized for load used.	S1 . Check powers involved as well as
		starting and operating currents.
	C2. Interference on supply lines.	S2. Check the supply line and if
		necessary install mains or 'surge' filters
		upstream of the cutting regulators.
	C3. By-pass configuration with short	S3 . Check input and output phase
After constitut for a contain	circuited phases.	correspondence.
After correctly operating for a certain time, cutting regulators supplies the	C1 . Lack of ventilation and/or high working temperature in the unit.	S1 . Check the unit is mounted vertically; check the room temperature
maximum voltage load regardless of	working temperature in the unit.	where the unit is installed.
control signal.	C2. Detection transducer faulty or short-	S2 . Check input control voltage (MA
	circuited.	terminal board).
Unit regulates load in ON - OFF	C1. Proportional band too "narrow"	S1 . Increase the proportional band value
operation.	with respect to system response.	with trimmer P2 .
	C2. CUT-OFF too high (80%).	S2 . Decrease value of P6 .
Unit has suspended regulation and Led	-	S1 . Check unit reset type (see position
TK ALARM is on.	intervened (contact MB 6,7).	of jumper J13). S2 .Check activation of the safety
		device and the cause of the intervention.
Unit has suspended regulation and Led	C1. A fuse has burnt out or one of	S1 . Replace supply line fuse and check
AC LINE ALARM is on.	supply phases is absent.	beginning of line upstream.
Output voltage constant even with		S1 . Select correct operating mode (NO
control signal activated and MANUAL	closed.	contact) by activating contacts 2,3 of
(Heat-Pump mode) Led is on.		terminal board MB.

8.0 LIABILITY AND RESIDUAL RISKS

Eliwell & Controlli s.r.l. shall not be liable for any damages deriving from:

- installation/use other than that prescribed and, in particular, that which does not comply with safety standards anticipated by regulations and/or those given herein;

- use on boards which do not guarantee adequate protection against electric shock, water or dust under the conditions of assembly applied;

- use on boards which allow access to dangerous parts without the use of tools;

- tampering with and/or alteration of the products;

- installation/use on boards not complying with the standards and provisions of current legislation.

9.0 DISCLAIMER

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TECHNICAL ASSISTANCE SHEET

- 1. All **rgf** equipment is guaranteed for **36** months from the date of testing.
- 2. The guarantee is rendered invalid under these circumstance:
- evidence of tampering with the mechanics or electrics
- incorrect installation

Ā

- improper use
- external electrical causes

Please keep this sheet near the 'rgf' regulator. To improve the assistance service and speed fault diagnosis, please fill this sheet in and send it to the Assistance centre together with the regulator in the event of a breakdown.

Customer:		Regulator	egulator model:				
Serial no.:	Date of	Date of installation:			Date of breakdown:		
	D	escription of the	fault				
 Noisy motor Unbalanced p Blocked motor 	hases 🗌 P	Surnt out motor rotection interrupt Differential interrupt		ohase R	Burnt fuse	phase T	
Description:							
Soft-Start		ols and contacts o			-1	0.1	
Prop.Band		/lax. Out. Lim. /lin. Out. Lim.	P4 P5		al contact contact	S1 S2	
Set-point		Cut-off	P6		P2 contact	S2 S3	
		Ianual (HP)	P7		contact	TK	
INPUT 4/20 m.		,			d. fd. 24 Vde	c / 40 mA	
INPUT 0/10 V	ic 🗌 C	Output 1		Potent	. fd. 10 Vdc	/ 5 mA	
☐ INPUT NTC		Output 2		RL1	B 10/9	B 10/8	
	Deta	ils of the connec	ted load				
Manufacturer:		Ту	pe 🗌	fans		lectric	
						sistors	
Electrical data	VAC Ar	np 🔄 Sta	rt amp.		Code		
	Motor			Ele	ctrical data		
Electrical data	star	🗌 delta	Phase R S	V	A	mp	
Traction	direct	belt driven	Phase S T	V	Α	mp	
Mechanics	helical	centrifugal	phase T R	V	А	mp	
Operator name:		Company st	amp:				
'		I					

Rgf300 INSTALLATION FEATURES

rgf FEATURES		FAN FEATURES				
Serial N°	N°	Model	Load (Amp)	Power Supply		
Model						

PROBE FEATURES

ТҮРЕ	N°	MODEL	RANGE	CONNECTION
Pressure Transducer				
NTC probe				
Transducer				

WORKING PARAMETERS

	TRIMMER	% OUTPUT	VAC OU	TPUT	VAC SUPPLY	FACTORY SETTING OPER	ATOR
P4 MAX. OUT							
P5 MIN. OUT							
P6 CUT-OFF							
P7	MANUAL						, m
	TRIMMER bar °C mA Vdc FACTORY SETTING OPERAT						ATOR
P2	PROP. BAND						
P3 SET-POINT 1							M
Р3	SET-POINT 1					SP1 N°:	
13	SET-POINT 2					SP2 N°:	
AU	AUXILIARI ON-OFFS1CONTACTSYESNO			S2	S3	RL1 D N.C.	N.O.
Date	: Operat	or Name :	Com	pany :			



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RGF 300 rel. 11/03 eng cod. 8MA10033